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LOCAL EXPLICIT MANY-KNOT SPLINE HERMITE APPROXIMATION SCHEMES.(U)  
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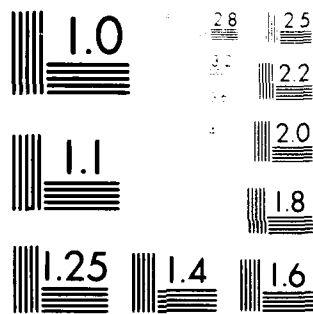
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MRC Technical Summary Report #2359

LOCAL EXPLICIT MANY-KNOT SPLINE  
HERMITE APPROXIMATION SCHEMES

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April 1982

(Received March 12, 1982)

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LOCAL EXPLICIT MANY-KNOT SPLINE HERMITE APPROXIMATION SCHEMES

D. X. Qi\* and S. Z. Zhou\*\*

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ABSTRACT

If  $f^{(i)}(\alpha)$  ( $\alpha = a, b$ ,  $i = 0, 1, \dots, k-1$ ) are given, then we get a class of the Hermite approximation operator  $Qf = F$  satisfying  $F^{(i)}(\alpha) = f^{(i)}(\alpha)$ , where  $F$  is the many-knot spline function whose knots are at points  $y_i : a = y_0 < y_1 < \dots < y_{k-1} = b$ , and  $F \in P_k$  on  $[y_{i-1}, y_i]$ . The operator is of the form  $Qf := \sum_{i=0}^{k-1} [f^{(i)}(a)\phi_i + f^{(i)}(b)\psi_i]$ . We give an explicit representation of  $\phi_i$  and  $\psi_i$  in terms of B-splines  $N_{i,k}$ . We show that  $Q$  reproduces appropriate classes of polynomials.

AMS (MOS) Subject Classification: 41A15

Key Words: Hermite interpolation, splines, local explicit, many-knot spline function.

Work Unit Number 3 (Numerical Analysis and Computer Science)

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# SIGNIFICANCE AND EXPLANATION

This paper deals with Hermite interpolation on the interval  $[a,b]$  using many-knot splines. The contribution of this paper is to find a many-knot spline function  $F$  of degree  $k - 1$  whose knots are at points  $y_i$ :

$$a = y_0 < y_1 < \dots < y_{k-1} = b.$$

When conditions are given on the ends of  $[a,b]$  :  $f^{(i)}(a)$ ,  $a = a,b$ ,  $i = 0, \dots, k - 1$ , then  $F = Qf = \sum_{i=0}^{k-1} [f^{(i)}(a)\phi_i + f^{(i)}(b)\psi_i]$  and  $F \in P_k$  on  $[y_{i-1}, y_i]$   $i = 1, 2, \dots, k - 1$ . The explicit representations of basic functions  $\phi_j, \psi_j$  which have properties

$$\phi_j^{(i)}(a) = \delta_{ij}, \quad \phi_j^{(i)}(b) = 0, \quad \psi_j^{(i)}(a) = 0, \quad \psi_j^{(i)}(b) = \delta_{ij}$$

$$\text{for all } i, j = 0, 1, \dots, k - 1$$

are given in terms of B-splines  $N_{i,k}$ . We also prove that this approximation operator  $Q$  reproduces appropriate classes of polynomials.

Since the degree of the many-knot splines used here is lower than that of ordinary Hermite interpolation and the knots of the splines can be chosen, it would be useful for some problems, for example, in Computer Aided Geometric Design (CAGD).



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# LOCAL EXPLICIT MANY-KNOT SPLINE HERMITE APPROXIMATION SCHEMES

D. X. Qi\* and S. Z. Zhou\*\*

## 1. INTRODUCTION

Some authors considered operators of the form  $Qf = \sum \lambda_i f N_{i,k}$ , where  $\{N_{i,k}\}$  is a sequence of B-splines and  $\{\lambda_i\}$  is a sequence of linear functionals. The variation diminishing method of Schoenberg ([9], [5], [6]), the quasi-interpolant of de Boor and Fix are well-known. Such approximation schemes have several important advantages over spline interpolation. They can be constructed directly without matrix inversion, local error bounds can be obtained naturally. Qi considered so-called many-knot splines which have many more knots than degrees of freedom and constructed the cardinal spline

$Qf = \sum f(x_i) q_{i,k}$ , where  $q_{i,k}$  is made up of B-splines on a uniform partition, has small support and satisfies  $q_{i,k}(x_j) = \delta_{ij}$ . [7] Such an approximation operator reproduces appropriate classes of polynomials [8]

The purpose of this paper is to construct a class of many-knot explicit local polynomial spline approximation operators for Hermite interpolation of real-valued functions defined on some interval  $[a, b]$ .

Let  $P_k$  be the set of polynomials of degree less than  $k$ , and let

$$a = y_0 < y_1 < \dots < y_{k-1} = b. \quad (1.0)$$

We define

$$\hat{S}_k := \{g : g|_{(y_i, y_{i+1})} \in P_k, i = 0, 1, \dots, k-2\}.$$

$\hat{S}_k$  is the familiar class of polynomial splines of order  $k$  with knots at the points  $y_i$  ( $i = 0, 1, \dots, k-2$ ).

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Let  $F$  be a linear space of real valued functions on  $[a,b]$ , and suppose  $F$  contains the class of polynomials  $P_k$ . Given  $f \in F$ , we construct an approximation  $F(\cdot) = Qf(\cdot)$  such that

$$f^{(l)}(a) = F^{(l)}(a), \quad F^{(l)}(b) = f^{(l)}(b) \quad l = 0, 1, \dots, k-1. \quad (1.1)$$

In other words, set

$$Qf := \sum_{j=0}^{k-1} f^{(j)}(a) \phi_j(x) + \sum_{j=0}^{k-1} f^{(j)}(b) \psi_j(x), \quad (1.2)$$

suppose  $\phi_j, \psi_j$  satisfying

$$\phi_j^{(i)}(a) = \delta_{ij}, \quad \phi_j^{(i)}(b) = 0 \quad (1.3)$$

$$\psi_j^{(i)}(a) = 0, \quad \psi_j^{(i)}(b) = \delta_{ij} \quad (1.4)$$

$$i, j = 0, 1, \dots, k-2.$$

If  $\phi_j$  and  $\psi_j$  are chosen in  $P_{2k-2}$ , then this problem above has been considered (see, for instance, [1], [3], [4]), and in this case  $F \in P_{2k-2}$  on  $[a,b]$ .

We will find a many-knot spline  $F \in \hat{S}_k$  satisfying (1.1). Such many-knot cardinal splines  $\{\phi_j\}$  and  $\{\psi_j\}$  are of degree less than  $k$ , therefore  $F$  is also of degree less than  $k$ . We present  $\phi_j$  and  $\psi_j$  as explicit representations.

This paper proves that the many-knot spline Hermite approximation operator  $Q$  reproduces appropriate classes of polynomials on  $[a,b]$ .

## 2. CONSTRUCTION OF $\phi_j$ AND $\psi_j$

Without loss of generality, we assume  $a = 0$  and  $b = 1$ . First of all set  $k = 3$  as an example.

Let  $\phi_0, \phi_1, \psi_0, \psi_1$  be piecewise polynomials of degree 2 with knots  $x = \frac{1}{2}$ , satisfying the following conditions

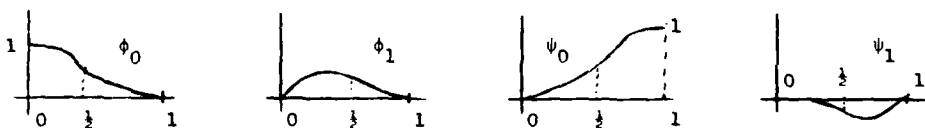
$$\begin{aligned} \phi_0(0) &= 1, & \phi_1'(0) &= 1, \\ \phi_0'(0) &= \phi_0'(1) = \phi_0'(1) = 0, & \phi_1(0) &= \phi_1(1) = \phi_1'(1) = 0, \\ \phi_0(\tfrac{1}{2} + 0) &= \phi_0(\tfrac{1}{2} - 0), & \phi_1(\tfrac{1}{2} + 0) &= \phi_1(\tfrac{1}{2} - 0), \\ \phi_0'(\tfrac{1}{2} + 0) &= \phi_0'(\tfrac{1}{2} - 0), & \phi_1'(\tfrac{1}{2} + 0) &= \phi_1'(\tfrac{1}{2} - 0). \end{aligned}$$

and  $\psi_0(x) := \phi_0(1-x)$ ,  $\psi_1(x) := -\phi_1(1-x)$ .

Easily one gets

$$\begin{aligned} \phi_0(x) &= \begin{cases} -2x^2 + 1, & x \in [0, \frac{1}{2}] , \\ 2(x-1)^2, & x \in [\frac{1}{2}, 1] ; \end{cases} \\ \phi_1(x) &= \begin{cases} -\frac{3}{2}x^2 + x, & x \in [0, \frac{1}{2}] , \\ \frac{1}{2}(x-1)^2, & x \in [\frac{1}{2}, 1] . \end{cases} \end{aligned}$$

Their graphs are sketched as follows





In order to consider the general case, denote

$$I_n := \{0, 1, \dots, n\}$$

$$\phi_j(x) := \sum_{\mu \in I_{k-1}} \alpha_{j,\mu} x^\mu, \quad x \in [x_i, x_{i+1}]$$

$$i \in I_{k-2}, \quad j \in I_{k-2}$$

(the partition is  $0 = x_0 < x_1 < x_2 < \dots < x_{k-1} = 1$ ), and

$$\phi_j^{(l)}(x_i - 0) = \phi_j^{(l)}(x_i + 0), \quad i \in I_{k-2} \setminus \{0\}, \quad l \in I_{k-2},$$

$$\phi_j^{(1)}(0) = \delta_{ij}, \quad \phi_j^{(1)}(1) = 0, \quad i, j \in I_{k-2}.$$

Since we have  $k(k-1)$  unknown coefficients  $\alpha_{j,\mu}$  with  $k(k-1)$  conditions, so it seems possible to find  $\alpha_{j,\mu}$ . But, it is difficult to get the explicit representations for  $\alpha_{j,\mu}$ . Below we will directly present the explicit formulas for  $\phi_j$  and  $\psi_j$ .

Here are the notations used in our discussion.

Let  $\underline{x} := (x_i)$  be a nondecreasing sequence. The  $i$ -th B-spline of order  $k$  for the knot sequence  $(x_i)$  is denoted by

$$N_{i,k}(x) := (x_{i+k} - x_i) [x_i, \dots, x_{i+k}] (-x)_+^{k-1}$$

for all  $x \in \mathbb{R}$ , where the symbol  $[x_i, \dots, x_{i+k}]$  denotes the  $k$ -th order divided-difference functional

$$\text{sym}_\mu(a_1, a_2, \dots, a_{n-1}) := \sum_{(v_1, \dots, v_\mu)} a_{v_1} a_{v_2} \dots a_{v_\mu}$$

$$v_j \in I_{n-1}, \quad v_i \neq v_j \quad (i \neq j)$$

$$\xi_1^{(\mu)} := \text{sym}_{\mu-1}(x_{i+1}, x_{i+1}, \dots, x_{i+k-1}) / \binom{k-1}{\mu-1}$$

$$\xi_1^{(0)} := \text{sym}_0(\dots) := 1.$$

From (1.0), we define

$$y_i - 1 =: x_i,$$

$$y_i =: x_{k-1+i}, \quad \text{for } i \in I_{k-1}.$$

(2.2)

Thus we get a partition on  $[-1,1]$  from  $[0,1]$ :

$$-1 = x_0 < x_1 < \dots < x_{k-2} < x_{k-1} = 0 < x_k < x_{k+1} < \dots < x_{2(k-1)} = 1. \quad (2.3)$$

We construct the following functions on  $[0,1]$  as a special kind of combination of B-splines

$$\phi_j(x) := \frac{1}{j!} \sum_{i \in I_{k-2}} \xi_i^{(j+1)} N_{i,k}(x), \quad (2.4)$$

for  $x \in [0,1]$ ,  $j \in I_{k-2}$ .

Theorem 1. The functions  $\phi_j(x)$  defined in (2.4) satisfy

$$\phi_j^{(l)}(0) = \delta_{lj}, \quad (2.5)$$

$$\phi_j^{(l)}(x) = 0 \text{ for } |x| > 1, \quad l, j \in I_{k-2}. \quad (2.6)$$

Proof. If  $i \in I_{k-2}$  and  $|x| > 1$ , then  $N_{i,k}^{(l)}(x) = 0$ , therefore  $\phi_j^{(l)}(x) = 0$  for all  $l, j \in I_{k-2}$  and  $|x| > 1$ . If  $i \notin I_{k-2}$ , then  $N_{i,k}^{(l)}(0) = 0$  since

$$I_{k-2} = \{i | i \in \{\dots, -2, -1, 0, 1, 2, \dots\}, N_{i,k}(0) \neq 0\}.$$

By Marsden's Identity<sup>[6]</sup>, for  $x \in [0,1]$

$$x^{\mu-1} = \sum_{i \in I_{2k-3}} \xi_i^{(\mu)} N_{i,k}(x), \quad \mu = 1, 2, \dots, k. \quad (2.7)$$

Thus

$$\begin{aligned} \phi_j^{(l)}(x) \Big|_{x=0} &= \left( \frac{1}{j!} \sum_{i \in I_{k-2}} \xi_i^{(j+1)} N_{i,k}(x) \right)^{(l)} \Big|_{x=0} \\ &= \frac{1}{j!} \left[ \left( \sum_{i \in I_{k-2}} + \sum_{i=k-1}^{2k-3} \right) \xi_i^{(j+1)} N_{i,k}(x) \right]^{(l)} \Big|_{x=0} \\ &= \frac{1}{j!} (x^j)^{(l)} \Big|_{x=0} = \delta_{lj}, \text{ for } l, j \in I_{k-2}. \end{aligned}$$

Let

$$\psi_j(x) := \phi_j(x-1)$$

Notice (2.2), (2.3), easily to see

$$\psi_j(x) = \frac{1}{j!} \sum_{i \in I_{k-2}} \xi_i^{(j+1)} N_{i+k-1,k}(x). \quad (2.8)$$

By (2.5) we get

$$\psi_j^{(l)}(0) = 0.$$

$$\psi_j^{(l)}(1) = \delta_{lj}, \text{ for } l, j \in I_{k-2}.$$

Examples:  $k = 3$ ,

$$\begin{pmatrix} \phi_0 \\ \phi_1 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ \alpha - \frac{1}{2} & \alpha \end{pmatrix} \begin{pmatrix} N_{0,3}(x) \\ N_{1,3}(x) \end{pmatrix},$$

$$\alpha = \text{sym}_1(y_0, y_1)/2 = \frac{y_0 + y_1}{2} = \frac{y_1}{2}.$$

When the partition is uniform, then

$$\phi_0 = N_{0,3}(x) + N_{1,3}(x),$$

$$\phi_1 = -\frac{1}{4} N_{0,3}(x) + \frac{1}{4} N_{1,3}(x).$$

$k = 4$ ,

$$\begin{pmatrix} \phi_0 \\ \phi_1 \\ \phi_2 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 \\ \alpha_1 - \frac{2}{3} & \alpha_1 - \frac{1}{3} & \alpha_1 \\ (\alpha_2 - \alpha_1 + \frac{1-y_0}{3})/2 & (\alpha_2 - \alpha_1 + \frac{y_2}{3})/2 & \alpha_2/2 \end{pmatrix} \begin{pmatrix} N_{0,4}(x) \\ N_{1,4}(x) \\ N_{2,4}(x) \end{pmatrix}, \quad x \in [0,1]$$

where

$$\alpha_1 = \text{sym}_1(y_0, y_1, y_2)/3 = \frac{y_0 + y_1 + y_2}{3},$$

$$\alpha_2 = \text{sym}_2(y_0, y_1, y_2)/3 = \frac{y_0 y_1 + y_1 y_2 + y_2 y_0}{3}.$$

In uniform case

$$\phi_0 = N_{0,4} + N_{1,4} + N_{2,4} ,$$

$$\phi_1 = -\frac{1}{3} N_{0,4} + \frac{1}{3} N_{2,4} , \quad x \in [0,1]$$

$$\phi_2 = \frac{2}{54} N_{0,4} - \frac{1}{54} N_{1,4} + \frac{2}{54} N_{2,4} .$$

### 3. THE OPERATOR Q REPRODUCES APPROPRIATE CLASSES OF POLYNOMIALS

Using the functions  $\phi_j$  and  $\psi_j$ , we have the following approximation operator

$$Qf(\cdot) := \sum_{j \in I_{k-2}} [f^{(j)}(0)\phi_j + f^{(j)}(1)\psi_j](\cdot) ,$$

Q defines a linear operator mapping  $F$  into  $\hat{S}_k$ .

Theorem 2.  $Qg = g$  for all  $g \in P_k$ .

Proof. Let

$$\text{span}(N) := \text{span}(N_{i,k}; i \in I_{2k-3}) ,$$

$$\text{span}(\phi, \psi) := \text{span}(\phi_j, \psi_j; j \in I_{k-2}) ,$$

$$S := \{g : Qg = g\} .$$

Then both  $\text{span}(N)$  and  $\text{span}(\phi, \psi)$  are linear subspaces of  $F$  on  $[0,1]$  of dimension  $2k - 2$ .

By (2.4) and (2.8) we have

$$\text{span}(\phi, \psi) \subseteq \text{span}(N) .$$

Since

$$\dim(\text{span}(\phi, \psi)) = \dim(\text{span}(N)) = 2k - 2 ,$$

$$\text{span}(\phi, \psi) = \text{span}(N)$$

Obviously

$$P_k \subseteq \text{span}(N)$$

i.e.

$$P_k \subseteq \text{span}(\phi, \psi)$$

Now it is sufficient to prove that

$$S = \text{span}(\phi, \psi) . \quad (3.1)$$

It follows from the definition of the set  $S$  and the operator  $Q$  that

$$S \subseteq \text{span}(\phi, \psi) . \quad (3.2)$$

On the other hand, Theorem 1 implies that we have  $Qf = f$  for any  $f \in \text{span}(\phi, \psi)$ .

Hence

$$\text{span}(\phi, \psi) \subseteq S . \quad (3.3)$$

(3.2) and (3.3) mean that (3.1) is valid.

#### ACKNOWLEDGMENT

We are deeply grateful to Professor Carl de Boor for his very valuable suggestions.

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REPORT DOCUMENTATION PAGE		READ INSTRUCTIONS BEFORE COMPLETING FORM
1. REPORT NUMBER 2359	2. GOVT ACCESSION NO. AD-A146 246	3. RECIPIENT'S CATALOG NUMBER
4. TITLE (and Subtitle)  LOCAL EXPLICIT MANY-KNOT SPLINE HERMITE APPROXIMATION SCHEMES		5. TYPE OF REPORT & PERIOD COVERED Summary Report - no specific reporting period
		6. PERFORMING ORG. REPORT NUMBER
7. AUTHOR(s)  D. X. Qi and S. Z. Zhou		8. CONTRACT OR GRANT NUMBER(s)  DAAG29-80-C-0041
9. PERFORMING ORGANIZATION NAME AND ADDRESS Mathematics Research Center, University of 610 Walnut Street Wisconsin Madison, Wisconsin 53706		10. PROGRAM ELEMENT, PROJECT, TASK AREA & WORK UNIT NUMBERS Work Unit Number 3 - Numerical Analysis and Computer Science
11. CONTROLLING OFFICE NAME AND ADDRESS U. S. Army Research Office P. O. Box 12211 Research Triangle Park, North Carolina 27709		12. REPORT DATE April 1982
14. MONITORING AGENCY NAME & ADDRESS (If different from Controlling Office)		13. NUMBER OF PAGES 8
		15. SECURITY CLASS. (of this report)  UNCLASSIFIED
		15a. DECLASSIFICATION/DOWNGRADING SCHEDULE
16. DISTRIBUTION STATEMENT (of this Report)  Approved for public release; distribution unlimited.		
17. DISTRIBUTION STATEMENT (of the abstract entered in Block 20, if different from Report)		
18. SUPPLEMENTARY NOTES		
19. KEY WORDS (Continue on reverse side if necessary and identify by block number)  Hermite interpolation, splines, local explicit, many-knot spline function		
20. ABSTRACT (Continue on reverse side if necessary and identify by block number)  If $f^{(i)}(\alpha)$ ( $\alpha = a, b, i = 0, 1, \dots, k-1$ ) are given, then we get a class of the Hermite approximation operator $Qf = F$ satisfying $F^{(i)}(\alpha) = f^{(i)}(\alpha)$ , where $F$ is the many-knot spline function whose knots are at points $y_i : a = y_0 < y_1 < \dots < y_{k-1} = b$ , and $F \in P_k$ on $[y_{i-1}, y_i]$ . The operator (cont.)		

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